

Two by Gel'fand and Pinsker

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Joint work with Ligong Wang.

Two Results of Gel'fand and Pinsker from 1980

Problems of Control and Information Theory, Vol. 9 (1), pp. 19–31 (1980)

CODING FOR CHANNEL WITH RANDOM PARAMETERS

S. I. GEL'FAND, M. S. PINSKER

(Moscow)

(Received January 20, 1979)

CAPACITY OF A BROADCAST CHANNEL WITH ONE DETERMINISTIC COMPONENT

S. I. Gel'fand and M. S. Pinsker

UDC 621.391.1

An internal bound is given for the capacity region of a two-output broadcast channel when there is common information. The capacity region for a broadcast channel with one deterministic component is computed. A noisy Blackwell channel is considered as an example.*

A Channel with Random Parameters

- Channel law

$$W(y|x, s), \quad \{S_k\} \sim \text{IID } P_S.$$

- The encoder knows the state sequence noncausally:

$$f: \mathcal{M} \times \mathcal{S}^n \rightarrow \mathcal{X}^n.$$

- \mathcal{M} is the message set

$$\mathcal{M} = \{1, \dots, 2^{nR}\}.$$

- R is the rate, and n is the blocklength.
- Decoder ignorant of state sequence:

$$\phi: \mathcal{Y}^n \rightarrow \mathcal{M}.$$

The highest rate of reliably communication

Gel'fand and Pinsker:

$$C = \max I(U; Y) - I(U; S)$$

where the maximum is over all PMFs

$$P_S(s) P_{U|S}(u|s) P_{X|S,U}(x|s, u) W(y|x, s).$$

And there is NLG in choosing $P_{X|S,U}$ deterministic:

$$P_S(s) P_{U|S}(u|s) I\{x = g(s, u)\} W(y|x, s)$$

$$C = \max_{P_{U|S}, g: S \times U \rightarrow \mathcal{X}} I(U; Y) - I(U; S)$$

Achievability

- Generate $2^{n(R+\tilde{R})}$ sequences IID P_U :

$$\mathbf{u}(m, \ell), \quad m \in \mathcal{M}, \ell \in \{1, \dots, 2^{n\tilde{R}}\}.$$

- To send Message m after observing \mathbf{s} , look for some ℓ such that $(\mathbf{u}(m, \ell), \mathbf{s})$ are j.t. w.r.t. $P_{S,U}$.
- If none found, “encoding failure.”
- The probability of encoding failure vanishes if

$$\tilde{R} > I(U; S).$$

- Decoder searches for a unique pair (m', ℓ') such that $(\mathbf{u}(m', \ell'), \mathbf{y})$ is j.t. w.r.t. $P_{U,Y}$.
- The probability of success tends to one if

$$R + \tilde{R} < I(U; Y).$$

The Converse

$$\begin{aligned} nR &\leq I(M; Y^n) + n\epsilon_n \\ &= \sum_i I(M; Y_i | Y^{i-1}) + n\epsilon_n \\ &= \sum_i I(M, S_{i+1}^n; Y_i | Y^{i-1}) - \sum_i I(S_{i+1}^n; Y_i | M, Y^{i-1}) + n\epsilon_n \\ &= \sum_i I(M, S_{i+1}^n; Y_i | Y^{i-1}) - \sum_i I(Y^{i-1}; S_i | M, S_{i+1}^n) + n\epsilon_n \\ &= \sum_i I(M, S_{i+1}^n; Y_i | Y^{i-1}) - \sum_i I(M, Y^{i-1}, S_{i+1}^n; S_i) + n\epsilon_n \\ &\leq \sum_i I(M, Y^{i-1}, S_{i+1}^n; Y_i) - \sum_i I(M, Y^{i-1}, S_{i+1}^n; S_i) + n\epsilon_n \\ &= \sum_i I(U_i; Y_i) - I(U_i; S_i) + n\epsilon_n. \end{aligned}$$

It only remains to check that

$$(M, Y^{i-1}, S_{i+1}^n) \text{---} (X_i, S_i) \text{---} Y_i.$$

What Is a Broadcast Channel?

- One transmitter and two receivers.
- Transmitted symbol: $X \in \mathcal{X}$.
- Received symbols: $Y \in \mathcal{Y}$ and $Z \in \mathcal{Z}$.
- Message $m_y \in \mathcal{M}_y$ for Receiver Y , and $m_z \in \mathcal{M}_z$ for Z .
- Channel is used n times (“the blocklength”).
- The rates are

$$R_y = \frac{\log \# \mathcal{M}_y}{n}, \quad R_z = \frac{\log \# \mathcal{M}_z}{n}.$$

- The encoder:

$$(m_y, m_z) \mapsto \mathbf{x}(m_y, m_z) = (x_1(m_y, m_z), \dots, x_n(m_y, m_z)) \in \mathcal{X}^n.$$

- The decoders:

$$\phi_y: \mathcal{Y}^n \rightarrow \mathcal{M}_y, \quad \phi_z: \mathcal{Z}^n \rightarrow \mathcal{M}_z.$$

The Probability of Error

A memoryless BC of law $W(y, z|x)$:

$$\Pr[\mathbf{Y} = \mathbf{y}, \mathbf{Z} = \mathbf{z} | \mathbf{X} = \mathbf{x}] = \prod_{k=1}^n W(y_k, z_k | x_k).$$

The probabilities of error:

$$\frac{1}{\#\mathcal{M}_y} \frac{1}{\#\mathcal{M}_z} \sum_{m_y \in \mathcal{M}_y} \sum_{m_z \in \mathcal{M}_z} \Pr[\phi_y(\mathbf{Y}) \neq m_y | M_y = m_y, M_z = m_z]$$

and

$$\frac{1}{\#\mathcal{M}_y} \frac{1}{\#\mathcal{M}_z} \sum_{m_y \in \mathcal{M}_y} \sum_{m_z \in \mathcal{M}_z} \Pr[\phi_z(\mathbf{Z}) \neq m_z | M_y = m_y, M_z = m_z].$$

Capacity Region

- (R_y, R_z) is achievable if for every $\epsilon > 0$ and $\delta > 0$ we are guaranteed that for all sufficiently large blocklengths n we can find encoder/decoders of rates $(R_y - \delta, R_z - \delta)$ for which both error probabilities are smaller than ϵ .
- Some special cases for which the capacity is known:
 - The degraded BC
 - Less Noisy
 - More capable
 - The deterministic BC
 - The semideterministic BC.

The Deterministic Broadcast Channel

$$Y = f_y(X), \quad Z = f_z(X)$$

for some

$$f_y: \mathcal{X} \rightarrow \mathcal{Y}, \quad f_z: \mathcal{X} \rightarrow \mathcal{Z}.$$

Gel'fand, Marton, and Pinsker: The capacity region is the convex closure of the union over all PMFs P_X of the (sets of) rate pairs

$$R_y \leq H(Y)$$

$$R_z \leq H(Z)$$

$$R_y + R_z \leq H(Y, Z)$$

where the entropies are computed for the joint PMF

$$P_{XYZ}(x, y, z) = P_X(x) \mathbf{1}\{y = f_y(x)\} \mathbf{1}\{z = f_z(x)\}.$$

The Converse for the Deterministic BC

The converse is easy:

$$I(M_y; \mathbf{Y}) \leq \sum_{k=1}^n H(Y_k),$$

$$I(M_z; \mathbf{Z}) \leq \sum_{k=1}^n H(Z_k),$$

and

$$I(M_y, M_z) \leq \sum_{k=1}^n H(Y_k, Z_k).$$

To bound R_y we ignore the fact that $H(\mathbf{Y}|M_y)$ is typically not zero (because of M_z). Likewise for R_z . And to bound $R_y + R_z$ we pretend that the receivers can cooperate.

Deterministic BC—the Direct Part

- Choose P_X , inducing a joint $P_X P_{Y|X} P_{Z|X}$ of marginal $P_{Y,Z}$.
- In two independent assignments, assign to each $\mathbf{y} \in \mathcal{Y}^n$ a random index $I \in \{1, \dots, 2^{nR_Y}\}$ and to each $\mathbf{z} \in \mathcal{Z}^n$ a random index $J \in \{1, \dots, 2^{nR_Z}\}$.
- Let $B(i, j)$ comprise the pairs (\mathbf{y}, \mathbf{z}) that are mapped to (i, j) .
- If (\mathbf{y}, \mathbf{z}) are jointly typical w.r.t. $P_{Y,Z}$, then there must exist some $\mathbf{x} \in \mathcal{X}^n$ that produces the outputs (\mathbf{y}, \mathbf{z}) , because joint typicality implies

$$\Pr[\mathbf{Y} = \mathbf{y}, \mathbf{Z} = \mathbf{z}] > 2^{-n(H(Y,Z)+\epsilon)} > 0,$$

and the only way this probability can be positive is if some \mathbf{x} induces these outputs.

- To send (m_Y, m_Z) look for a pair (\mathbf{y}, \mathbf{z}) in $B(m_Y, m_Z)$ that is jointly typical, and transmit the sequence \mathbf{x} that produces it.
- If there is no j.t. (\mathbf{y}, \mathbf{z}) in $B(m_Y, m_Z)$, \Rightarrow “encoding failure.”

The Semideterministic Broadcast Channel

Only Y is deterministic given x :

$$Y = f_y(x), \quad \Pr[Z = z | X = x] = W(z|x).$$

Gel'fand and Pinsker: The capacity is the convex hull of the union over all P_X of the sets of rate pairs (R_y, R_z)

$$R_y < H(Y)$$

$$R_z < I(U; Z)$$

$$R_y + R_z < H(Y) + I(U; Z) - I(U; Y)$$

over all joint distribution on (X, Y, Z, U) under which, conditional on X , the channel outputs Y and Z are drawn according to the channel law independently of U :

$$P_{XYZU}(x, y, z, u) = P_{X,U}(x, u) \mathbf{1}\{y = f_y(x)\} W(z|x).$$

Achievability follows from Marton's Inner Bound (More later).

State-Dependence and Prescience

- A state sequence S_1, \dots, S_n is generated IID $\sim P_S$. The channel law is

$$W(y, z | \mathbf{s}, \mathbf{x}).$$

- A prescient encoder knows S_1, \dots, S_n before transmission begins:

$$\mathbf{x} = \mathbf{x}(m_y, m_z, \mathbf{s}).$$

State-Dependence and Prescience

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- A prescient encoder knows S_1, \dots, S_n before transmission begins:

$$\mathbf{x} = \mathbf{x}(m_y, m_z, \mathbf{s}).$$

At least as hard as the BC without a state. . . .

The Steinberg-Shamai Inner Bound

Achievability of (R_1, R_2) is guaranteed whenever

$$R_1 \leq I(U_0, U_1; Y) - I(U_0, U_1; S)$$

$$R_2 \leq I(U_0, U_2; Z) - I(U_0, U_2; S)$$

$$\begin{aligned} R_1 + R_2 \leq & -[\max\{I(U_0; Y), I(U_0; Z)\} - I(U_0; S)]^+ \\ & + I(U_0, U_1; Y) - I(U_0, U_1; S) \\ & + I(U_0, U_2; Z) - I(U_0, U_2; S) - I(U_1; U_2|U_0, S), \end{aligned}$$

for some PMF of marginal P_S ; that satisfies

$$(U_0, U_1, U_2) \text{---} \circ \text{---} (X, S) \text{---} \circ \text{---} (Y, Z);$$

with the conditional of (Y, Z) given (X, S) being $W(y, z|x, s)$.

The Semideterministic State-Dependent BC with a Prescient Transmitter

- Y is a deterministic function of (x, s) but Z possibly not:

$$Y = f(s, x), \quad \Pr[Z = z | X = x, S = s] = W(z|x, s).$$

- The transmitter has noncausal state-information:

$$(m_y, m_z, \mathbf{s}) \mapsto \mathbf{x}(m_y, m_z, \mathbf{s}) = (x_1(m_y, m_z, \mathbf{s}), \dots, x_n(m_y, m_z, \mathbf{s})).$$

Two Special Cases

- State is null \implies (classical) semideterministic BC.

(Gel'fand and Pinsker'80b).

Two Special Cases

- State is null \implies (classical) semideterministic BC.
(Gel'fand and Pinsker'80b).
- Y is null \implies the single-user "Gel'fand-Pinsker problem"
(Gel'fand and Pinsker'80a):

$$C = \max_{U \rightarrow (X,S) \rightarrow Z} I(U; Z) - I(U; S)$$

where the maximization is over PMFs of the form

$$P_S(s) P_{U|S}(u|s) P_{X|S,U}(x|s, u) W(z|x, s),$$

and $P_{X|S,U}$ can be taken to be deterministic.

Who Is S.I Gel'fand?

Who Is S.I Gel'fand?

Sergey Israilevich Gel'fand.
Ph.D. 1968
Moscow State Univeristy

Supervisor: A. A. Kirillov.



Israil Moiseevich Gel'fand (father)



The Main Result

The capacity region is convex closure of the union of rate-pairs (R_y, R_z) satisfying

$$R_y < H(Y|S)$$

$$R_z < I(U; Z) - I(U; S)$$

$$R_y + R_z < H(Y|S) + I(U; Z) - I(U; S, Y)$$

over all joint distribution on (X, Y, Z, S, U) whose marginal P_S is the given state distribution and under which, conditional on X and S , the channel outputs Y and Z are drawn according to the channel law independently of U :

$$P_{XYZSU}(x, y, z, s, u) = P_S(s)P_{XU|S}(x, u|s)\mathbf{1}\{y = f(x, s)\}W(z|x, s).$$

Moreover, the capacity region is unchanged if the state sequence is revealed to the deterministic receiver.

If the State Is Null

$$R_y < H(Y|S)$$

$$R_z < I(U; Z) - I(U; S) \xrightarrow{0}$$

$$R_y + R_z < H(Y|S) + I(U; Z) - I(U; S, Y) \xrightarrow{I(U; Y)}$$

$$P_{XYZSU}(x, y, z, s, u) = P_S(s) P_{XU|S}(x, u|s) \mathbf{1}\{y = f(x, s)\} W(z|x, s).$$

That is,

$$R_y < H(Y)$$

$$R_z < I(U; Z)$$

$$R_y + R_z < H(Y) + I(U; Z) - I(U; Y)$$

$$P_{XYZU}(x, y, z, u) = P_{XU}(x, u) \mathbf{1}\{y = f(x)\} W(z|x).$$

If the Deterministic Receiver Is Null

$$\cancel{R_y} < \cancel{H(Y|S)}$$

$$R_z < I(U; Z) - I(U; S)$$

$$\cancel{R_y} + R_z < \cancel{H(Y|S)} + I(U; Z) - \cancel{I(U; S, Y)} \xrightarrow{0} I(U; S)$$

$$P_{\cancel{X} \cancel{Y} Z S U}(x, \cancel{y}, z, s, u) = P_S(s) P_{XU|S}(x, u|s) \mathbf{1}_{\{\cancel{y} = \cancel{f}(x, s)\}} W(z|x, s).$$

If the Deterministic Receiver Is Null

$$\cancel{R_y} < \cancel{H(Y|S)}$$

$$R_z < I(U; Z) - I(U; S)$$

$$\cancel{R_y} + R_z < \cancel{H(Y|S)} + I(U; Z) - \cancel{I(U; S, Y)} \xrightarrow{I(U; S)}$$

$$P_{\cancel{X}Y\cancel{Z}SU}(x, \cancel{y}, z, s, u) = P_S(s) P_{XU|S}(x, u|s) \mathbf{1}\{\cancel{y} = \cancel{f(x, s)}\} W(z|x, s).$$

Third and second constraints are identical and

$$R_z < I(U; Z) - I(U; S)$$

$$P_{XZSU}(x, z, s, u) = P_S(s) P_{XU|S}(x, u|s) W(z|x, s).$$

Previous Work

- On the degraded BC, see

Y. Steinberg, "Coding for the degraded broadcast channel with random parameters, with causal and noncausal side information," *IEEE Trans. Inform. Theory*, vol. 51, no. 8, pp. 2867–2877, Aug. 2005.

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- On the degraded BC, see

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- Reza Khosravi and Farokh Marvasti solved the following special cases of our setting:
 - The deterministic case.
 - The case where S is also known to the nondeterministic receiver Z .
 - The degraded case, from the deterministic to the noisy:

$$W(z|x, s) = \tilde{W}(z|y).$$

"Capacity Bounds for Multiuser Channels with Non-Causal Channel State Information at the Transmitters," arXiv:1102.3410v2 (Feb. and May 2011).

The Achievability—the Proof for Yossi and Shlomo

Substitute in the Steinberg-Shamai inner bound

$$U_0 = 0, \quad U_1 = Y, \quad U_2 = U.$$

$$R_1 \leq I(\cancel{U_0}, \cancel{U_1}; \overset{Y}{Y}) - I(\cancel{U_0}, \cancel{U_1}; \overset{Y}{S})$$

$$R_2 \leq I(\cancel{U_0}, \cancel{U_2}; Z) - I(\cancel{U_0}, \cancel{U_2}; S)$$

$$\begin{aligned} R_1 + R_2 &\leq -[\max\{I(U_0; Y), I(U_0; Z)\} - I(U_0; S)]^+ \\ &\quad + I(\cancel{U_0}, \cancel{U_1}; \overset{Y}{Y}) - I(\cancel{U_0}, \cancel{U_1}; \overset{Y}{S}) \\ &\quad + I(\cancel{U_0}, \cancel{U_2}; Z) - I(\cancel{U_0}, \cancel{U_2}; S) - I(\overset{Y}{U_1}; \overset{Y}{U_2} | \cancel{U_0}, S), \end{aligned}$$

$$\begin{aligned}
 R_1 &\leq H(Y) - I(Y; S) && \xrightarrow{H(Y|S)} \\
 R_2 &\leq I(U_2; Z) - I(U_2; S) \\
 R_1 + R_2 &\leq H(Y) - I(Y; S) + I(U_2; Z) && \xrightarrow{H(Y|S)} \\
 &\quad - I(U_2; S) - I(Y; U_2|S). && \xrightarrow{-I(U_2; S, Y)}
 \end{aligned}$$

The condition

$$(U_0, U_1, U_2) \circ - (X, S) \circ - (Y, Z)$$

becomes

$$(Y, U_2) \circ - (X, S) \circ - (Y, Z),$$

which, because Y is a deterministic function of (X, S) , holds whenever

$$U_2 \circ - (X, S) \circ - Z.$$

Achievability for Mortals

Fix some P_{XYZSU} of the form

$$P_{XYZSU}(x, y, z, s, u) = P_S(s)P_{XU|S}(x, u|s)\mathbf{1}\{y = f(x, s)\}W(z|x, s).$$

Achievability for Mortals

Fix some P_{XYZSU} of the form

$$P_{XYZSU}(x, y, z, s, u) = P_S(s)P_{XU|S}(x, u|s)\mathbf{1}\{y = f(x, s)\}W(z|x, s).$$

Sum over z to obtain $P_{SU\Upsilon X}$ and write it as

$$P_{SU\Upsilon}(s, u, y) P_{X|S,U,\Upsilon}(x|s, u, y).$$

Achievability for Mortals

Fix some P_{XYZSU} of the form

$$P_{XYZSU}(x, y, z, s, u) = P_S(s)P_{XU|S}(x, u|s)\mathbf{1}\{y = f(x, s)\}W(z|x, s).$$

Sum over z to obtain $P_{SU\bar{Y}X}$ and write it as

$$P_{SU\bar{Y}X}(s, u, y) P_{X|S, U, \bar{Y}}(x|s, u, y).$$

For fixed $P_{SU\bar{Y}X}$, only the terms in red depend on $P_{X|S, U, \bar{Y}}$:

$$R_y < H(Y|S)$$

$$R_z < I(U; Z) - I(U; S)$$

$$R_y + R_z < H(Y|S) + I(U; Z) - I(U; S, Y)$$

Achievability for Mortals

Fix some P_{XYZSU} of the form

$$P_{XYZSU}(x, y, z, s, u) = P_S(s)P_{XU|S}(x, u|s)\mathbf{1}\{y = f(x, s)\}W(z|x, s).$$

Sum over z to obtain $P_{SU YX}$ and write it as

$$P_{SU Y}(s, u, y) P_{X|S, U, Y}(x|s, u, y).$$

For fixed $P_{SU Y}$, only the terms in red depend on $P_{X|S, U, Y}$:

$$R_y < H(Y|S)$$

$$R_z < I(U; Z) - I(U; S)$$

$$R_y + R_z < H(Y|S) + I(U; Z) - I(U; S, Y)$$

so, by convexity, we can assume that $P_{X|S, U, Y}$ is zero-one-valued:

$$g: (y, u, s) \mapsto x.$$

The Reduction

Henceforth we only consider joint PMFs satisfying

$$P_{XYZSU}(x, y, z, s, u) = P_S(s)P_{YU|S}(y, u|s)\mathbf{1}\{x = g(y, u, s)\}W(z|x, s)$$

and

$$Y = f(S, X).$$

Codebook and Encoder

Generate 2^{nR_y} y -bins, each containing $2^{n\tilde{R}_y}$ y -tuples IID $\sim P_Y$

$$\mathbf{y}(m_y, l_y), \quad m_y \in \{1, \dots, 2^{nR_y}\}, \quad l_y \in \{1, \dots, 2^{n\tilde{R}_y}\}.$$

Codebook and Encoder

Generate 2^{nR_y} y -bins, each containing $2^{n\tilde{R}_y}$ y -tuples IID $\sim P_Y$

$$\mathbf{y}(m_y, l_y), \quad m_y \in \{1, \dots, 2^{nR_y}\}, \quad l_y \in \{1, \dots, 2^{n\tilde{R}_y}\}.$$

Independently of that, generate 2^{nR_z} u -bins, each containing $2^{n\tilde{R}_z}$ u -tuples IID $\sim P_U$

$$\mathbf{u}(m_z, l_z), \quad m_z \in \{1, \dots, 2^{nR_z}\}, \quad l_z \in \{1, \dots, 2^{n\tilde{R}_z}\}.$$

Codebook and Encoder

Generate 2^{nR_y} y -bins, each containing $2^{n\tilde{R}_y}$ y -tuples IID $\sim P_Y$

$$\mathbf{y}(m_y, l_y), \quad m_y \in \{1, \dots, 2^{nR_y}\}, \quad l_y \in \{1, \dots, 2^{n\tilde{R}_y}\}.$$

Independently of that, generate 2^{nR_z} u -bins, each containing $2^{n\tilde{R}_z}$ u -tuples IID $\sim P_U$

$$\mathbf{u}(m_z, l_z), \quad m_z \in \{1, \dots, 2^{nR_z}\}, \quad l_z \in \{1, \dots, 2^{n\tilde{R}_z}\}.$$

To send (m_y, m_z) look for a y -tuple $\mathbf{y}(m_y, l_y)$ in y -bin m_y and a u -tuple $\mathbf{u}(m_z, l_z)$ in u -bin m_z such that

$$(\mathbf{y}(m_y, l_y), \mathbf{u}(m_z, l_z), \mathbf{s}) \text{ are jointly typical } P_{YUS}.$$

If such a pair can be found, send (componentwise)

$$\mathbf{x} = g(\mathbf{y}(m_y, l_y), \mathbf{u}(m_z, l_z), \mathbf{s}).$$

Analysis: The Deterministic Decoder Errs:

- The deterministic receiver observes $\mathbf{y}(m_y, l_y)$.
- It errs only if

$$\mathbf{y}(m_y, l_y) = \mathbf{y}(m'_y, l'_y), \quad \text{for } m'_y \neq m_y.$$

- This probability of error tends to zero whenever

$$R_y + \tilde{R}_y < H(Y).$$

Analysis: The Nondeterministic Decoder Errs:

- The nondeterministic decoder searches for a unique pair (m_z, l_z) such that $u(m_z, l_z)$ & \mathbf{z} are jointly typical.
- The probability of error tends to zero if

$$R_z + \tilde{R}_z < I(U; Z).$$

Analysis: An Encoding Error

- Encoding error: We cannot find a pair (l_y, l_z) such that $(\mathbf{y}(m_y, l_y), \mathbf{u}(m_z, l_z), \mathbf{s})$ are jointly typical P_{YUS} .

Analysis: An Encoding Error

- Encoding error: We cannot find a pair (l_y, l_z) such that $(\mathbf{y}(m_y, l_y), \mathbf{u}(m_z, l_z), \mathbf{s})$ are jointly typical P_{YUS} .
- For the probability of this event to tend to zero it suffices that:
 - For every fixed j.t. (\mathbf{u}, \mathbf{s}) , the expected number of \mathbf{y} 's in y -Bin(m_y) that are j.t. with (\mathbf{u}, \mathbf{s}) be exponentially large.
 - For every fixed j.t. (\mathbf{y}, \mathbf{s}) , the expected number of \mathbf{u} 's in u -Bin(m_z) that are j.t. with (\mathbf{y}, \mathbf{s}) be exponentially large.
 - For every fixed typical \mathbf{s} , the expected number of (l_y, l_z) pairs such that $(\mathbf{y}(m_y, l_y), \mathbf{u}(m_z, l_z), \mathbf{s})$ are jointly typical be exponentially large.

Analysis: An Encoding Error

- Encoding error: We cannot find a pair (l_y, l_z) such that $(\mathbf{y}(m_y, l_y), \mathbf{u}(m_z, l_z), \mathbf{s})$ are jointly typical P_{YUS} .
- For the probability of this event to tend to zero it suffices that:
 - For every fixed j.t. (\mathbf{u}, \mathbf{s}) , the expected number of \mathbf{y} 's in y -Bin(m_y) that are j.t. with (\mathbf{u}, \mathbf{s}) be exponentially large.
 - For every fixed j.t. (\mathbf{y}, \mathbf{s}) , the expected number of \mathbf{u} 's in u -Bin(m_z) that are j.t. with (\mathbf{y}, \mathbf{s}) be exponentially large.
 - For every fixed typical \mathbf{s} , the expected number of (l_y, l_z) pairs such that $(\mathbf{y}(m_y, l_y), \mathbf{u}(m_z, l_z), \mathbf{s})$ are jointly typical be exponentially large.
- Hence, it suffices that

$$\tilde{R}_y > I(Y; S)$$

$$\tilde{R}_z > I(U; S)$$

$$\tilde{R}_y + \tilde{R}_z > H(Y) + H(U) + H(S) - H(Y, U, S).$$

Concluding the Achievability Proof

The constraints

$$R_y + \tilde{R}_y < H(Y) \quad (\text{a})$$

$$R_z + \tilde{R}_z < I(U; Z) \quad (\text{b})$$

$$\tilde{R}_y > I(Y; S) \quad (\text{c})$$

$$\tilde{R}_z > I(U; S) \quad (\text{d})$$

$$\tilde{R}_y + \tilde{R}_z > H(Y) + H(U) + H(S) - H(Y, U, S). \quad (\text{e})$$

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allow the achievability of

$$R_y < H(Y|S) \quad \text{from (a) and (c)}$$

$$R_z < I(U; Z) - I(U; S) \quad \text{from (b) and (d)}$$

$$R_y + R_z < H(Y|S) + I(U; Z) - I(U; S, Y) \quad \text{from (a)+(b) and (e)}$$

(Constraint (e) pinches more than (c) + (d).)

The Converse I

Upper-bounding R_y is straightforward:

$$\begin{aligned} nR_y &= H(M_y) \\ &\leq I(M_y; Y^n, S^n) + n\epsilon_n \\ &= I(M_y; Y^n | S^n) + n\epsilon_n \\ &= \sum_{i=1}^n I(M_y; Y_i | Y^{i-1}, S^n) + n\epsilon_n \\ &\leq \sum_{i=1}^n H(Y_i | Y^{i-1}, S^n) + n\epsilon_n \\ &\leq \sum_{i=1}^n H(Y_i | S_i) + n\epsilon_n, \end{aligned}$$

where ϵ_n decays to zero as n tends to infinity.

The Converse II

Upper-bounding R_Z à-la-Gelf'and-Pinsker (first approach):

$$\begin{aligned} nR_2 &\leq I(M_Z; Z^n) + n\epsilon_n \\ &= \sum_i I(M_Z; Z_i | Z^{i-1}) + n\epsilon_n \\ &= \sum_i I(M_Z, S_{i+1}^n; Z_i | Z^{i-1}) - \sum_i I(S_{i+1}^n; Z_i | M_Z, Z^{i-1}) + n\epsilon_n \\ &= \sum_i I(M_Z, S_{i+1}^n; Z_i | Z^{i-1}) - \sum_i I(Z^{i-1}; S_i | M_Z, S_{i+1}^n) + n\epsilon_n \\ &= \sum_i I(M_Z, S_{i+1}^n; Z_i | Z^{i-1}) - \sum_i I(M_Z, Z^{i-1}, S_{i+1}^n; S_i) + n\epsilon_n \\ &\leq \sum_i I(M_Z, Z^{i-1}, S_{i+1}^n; Z_i) - \sum_i I(M_Z, Z^{i-1}, S_{i+1}^n; S_i) + n\epsilon_n \\ &= \sum_i I(V_i; Z_i) - I(V_i; S_i) + n\epsilon_n. \end{aligned}$$

The Converse III

Upper-bounding the sum-rate:

$$\begin{aligned}n(R_y + R_z) &= H(M_y, M_z) \\ &= H(M_z) + H(M_y|M_z) \\ &\leq I(M_z; Z^n) + I(M_y; Y^n, S^n|M_z) + n\epsilon_n.\end{aligned}$$

The Converse IV

Another bound on $I(M_Z; Z^n)$:

$$\begin{aligned} I(M_Z; Z^n) &= \sum_i I(M_Z; Z_i | Z^{i-1}) \\ &\leq \sum_i I(M_Z, Z^{i-1}; Z_i) \\ &= \sum_i I(M_Z, Z^{i-1}, S_{i+1}^n, Y_{i+1}^n; Z_i) - \sum_i I(S_{i+1}^n, Y_{i+1}^n; Z_i | M_Z, Z^{i-1}) \\ &= \sum_i I(M_Z, Z^{i-1}, S_{i+1}^n, Y_{i+1}^n; Z_i) - \sum_i I(Z^{i-1}; S_i, Y_i | M_Z, S_{i+1}^n, Y_{i+1}^n) \\ &= \sum_i I(M_Z, Z^{i-1}, S_{i+1}^n, Y_{i+1}^n; Z_i) - \sum_i I(M_Z, Z^{i-1}, S_{i+1}^n, Y_{i+1}^n; S_i, Y_i) \\ &\quad + \sum_i I(M_Z, S_{i+1}^n, Y_{i+1}^n; S_i, Y_i). \end{aligned}$$

The Converse V

The last term and $I(M_y; Y^n, S^n | M_z)$ add to

$$\sum_{i=1}^n I(M_z, S_{i+1}^n, Y_{i+1}^n; S_i, Y_i) + I(M_y; Y^n, S^n | M_z) = \sum_{i=1}^n H(Y_i | S_i).$$

(After lots of identities).

The Converse VI

$$\begin{aligned} & n(R_y + R_z) \\ & \leq \sum_i I(M_z, Z^{i-1}, S_{i+1}^n, Y_{i+1}^n; Z_i) \\ & \quad - \sum_i I(M_z, Z^{i-1}, S_{i+1}^n, Y_{i+1}^n; S_i, Y_i) \\ & \quad + \sum_{i=1}^n H(Y_i|S_i) + n\epsilon_n \\ & = \sum_{i=1}^n I(V_i, T_i; Z_i) - \sum_{i=1}^n I(V_i, T_i; S_i, Y_i) + \sum_{i=1}^n H(Y_i|S_i) + n\epsilon_n. \end{aligned}$$

The Converse VII

We have:

$$R_y < H(Y|S)$$

$$R_z < I(V; Z) - I(V; S)$$

$$R_y + R_z < H(Y|S) + I(V, T; Z) - I(V, T; S, Y).$$

$$(V, T) \text{---} \circ \text{---} (X, S) \text{---} \circ \text{---} (Y, Z).$$

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We want:

$$R_y < H(Y|S)$$

$$R_z < I(U; Z) - I(U; S)$$

$$R_y + R_z < H(Y|S) + I(U; Z) - I(U; S, Y)$$

$$U \text{---} \circ \text{---} (X, S) \text{---} \circ \text{---} (Y, Z).$$

The Converse IIX

We are looking for an auxiliary r.v. U such that

$$U \circ - (X, S) \circ - (Y, Z).$$

for which

$$I(V; Z) - I(V; S) \leq I(U; Z) - I(U; S)$$

and

$$\cancel{H(Y|S)} + I(V, T; Z) - I(V, T; S, Y) \leq \cancel{H(Y|S)} + I(U; Z) - I(U; S, Y)$$

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Choosing U as V will work if

$$I(T; Z|V) - I(T; S, Y|V) \leq 0.$$

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Choosing U as (V, T) will work if

$$I(T; Z|V) - I(T; S|V) \geq 0.$$

The Converse IX

At least one of the conditions

$$I(T; Z|V) - I(T; S, Y|V) \leq 0$$

and

$$I(T; Z|V) - I(T; S|V) \geq 0$$

must hold:

The Converse IX

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$$I(T; Z|V) - I(T; S, Y|V) \leq 0$$

and

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must hold: having the first be positive and the second negative violates

$$I(T; Z|V) - I(T; S, Y|V) \leq I(T; Z|V) - I(T; S|V).$$

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must hold: having the first be positive and the second negative violates

$$I(T; Z|V) - I(T; S, Y|V) \leq I(T; Z|V) - I(T; S|V).$$

The latter holds because

$$\cancel{I(T; Z|V)} - I(T; S|V) - (\cancel{I(T; Z|V)} - I(T; S, Y|V)) = I(T; Y|S, V)$$

and is thus nonnegative.

Thank you.

Cardinality Bounds

$$\#\mathcal{U} \leq (\#\mathcal{S})(\#\mathcal{X}) + 2.$$